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| 1 (i) | $\begin{aligned} & 15+F \cos 60^{\circ}=F \cos 30^{\circ} \\ & F=41.0 \end{aligned}$ | $\begin{gathered} \text { M1 } \\ \text { A1 } \\ \text { A1 } \end{gathered}$ | 3 | For resolving forces in the $x$ direction $\mathbf{A G} \quad F=15(1+\sqrt{3})$ |
| :---: | :---: | :---: | :---: | :---: |
| (ii) | $\left[G=F\left(\sin 30^{\circ}+\sin 60^{\circ}\right)\right]$ $G=56.0$ | $\begin{gathered} \text { M1 } \\ \text { A1 } \end{gathered}$ | 2 | For resolving forces in the $y$ direction <br> Allow $15(2+\sqrt{3})$ |
| 2 (i) | $\left[V^{2}=(V-10)^{2}+2 g \times 35\right]$ $\begin{aligned} & 20 V=100+70 g \\ & V=40 \end{aligned}$ | M1 <br> A1 <br> A1 | 3 | For using $v^{2}=u^{2}+2 g s$ to obtain an equation in $V$ only or to obtain two equations in $V$ and $H$ and attempting to eliminate $H$ |
| Alternative for 2(i) |  |  |  |  |
| (i) | $\begin{aligned} & V=V-10+10 t \rightarrow t=1 \text { and } \\ & 35=(V-10) \times 1+1 / 2 \times 10 \times 1^{2} \text { or } \\ & 35=(V-10+V) / 2 \times 1 \\ & V=40 \end{aligned}$ | M1 <br> A1 <br> A1 | 3 | A complete method to find $V$ by considering the final 35 m using $v=u+a t$ and either $s=u t+1 / 2 a t^{2} \text { or } s=(u+v) / 2 \times t$ |
| (ii) | $\begin{aligned} & {\left[40^{2}=0^{2}+20 H\right]} \\ & H=80 \end{aligned}$ | $\begin{aligned} & \text { M1 } \\ & \text { A1 } \end{aligned}$ | 2 | For using $v^{2}=u^{2}+2 g s$ |
| 3 (i) | $\begin{aligned} {[a(t)} & \left.=0.00012 t^{2}-0.012 t+0.288\right] \\ {[a(t)} & =0.00012\left(t^{2}-100 t+2400\right) \\ & =0.00012(t-40)(t-60)=0] \\ a(t) & =0 \text { when } t=40 \text { and } t=60 \end{aligned}$ | M1* <br> dM1* <br> A1 | 3 | For attempting to differentiate $v(t)$ <br> For setting $a(t)=0$ and attempting to solve a three term quadratic |
| (ii) | $\begin{aligned} & {\left[0.00001 t^{4}-0.002 t^{3}+0.144 t^{2}\right]} \\ & {\left[0.00001(100)^{4}-0.002(100)^{3}+\right.} \\ & \left.0.144(100)^{2}\right] \end{aligned}$ <br> Displacement is 440 m | $\begin{gathered} \text { M1 } \dagger \\ \text { dM1 } \dagger \\ \text { A1 } \end{gathered}$ | 3 | For attempting to integrate $v(t)$ <br> Integration attempted using correct limits $t$ $=0 \text { to } t=100$ |


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| 4 | $\begin{aligned} \text { Frictional force } & =0.4 \times 2 \cos 45 \\ & =0.4 \sqrt{2} \end{aligned}$ <br> KE gain $=1 / 2 \times 0.2 \times V_{\mathrm{C}}^{2}$ and <br> PE loss $=0.2 \times g \times(2.5+2 \sqrt{2})$ $0.1 V_{\mathrm{C}}^{2}=(5+4 \sqrt{2})-0.4 \sqrt{2} \times 4$ <br> Speed at $C$ is $9.16 \mathrm{~ms}^{-1}$ | M1 <br> A1 <br> B1 <br> M1 <br> A1 | 6 | For using $R=2 \cos 45^{\circ}$ <br> and $F=\mu R$ <br> For using KE gain from $A$ to $C$ $=$ PE loss from $A$ to $C$ - Work done by frictional force |
| :---: | :---: | :---: | :---: | :---: |

First alternative for the last four marks


Second alternative for the last four marks


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\begin{tabular}{|c|c|c|c|c|}
\hline 5 (i) \& \begin{tabular}{l}
\[
\begin{aligned}
\& 0.5 g \times \frac{7}{25}-T=0.5 a \\
\& T-0.1 g=0.1 a \\
\& 1.4-1=0.6 a
\end{aligned}
\] \\
For eliminating \(T\) and obtaining
\[
a=\frac{2}{3} \mathrm{~ms}^{-2}
\] \\
Tension is 1.07 N
\end{tabular} \& M1

A1

B1
M1

A1 \& 5 \& | For applying Newton $2^{\text {nd }}$ law to $P$ or to $Q$ or for applying N 2 to the system |
| :--- |
| Any two correct |
| Allow $\sin 16.3$ for $7 / 25$ |
| For substituting for $a$ to find $T$ |
| Allow $T=16 / 15 \mathrm{~N}$ | \\

\hline (ii) \& | $\left[v^{2}=2 \times\left(\frac{2}{3}\right) \times 0.7\right]$ $\left[2^{2}=2 \times \frac{2}{3} \times 0.7+2 \times 0.28 g \times s\right]$ |
| :--- |
| Length of string $=2.5-s=1.95 \mathrm{~m}$ | \& | M1 |
| :--- |
| M1 |
| A1 | \& 3 \& | For using $v^{2}=u^{2}+2$ as to find the speed of the particles immediately before the string breaks |
| :--- |
| For applying $v^{2}=u^{2}+2 a s$ for the motion of $P$ when the string is slack and $s$ is the distance travelled by $P$ after the break until it reaches the floor |
| Allow length $=41 / 21 \mathrm{~m}$ | \\


\hline 6 (i) \& | $\begin{aligned} & {[0.195 \cos \theta=F]} \\ & \begin{aligned} F & =0.195 \cos 22.6=0.195 \times \frac{12}{13} \\ & =0.18=\frac{9}{50} \\ {[R} & =0.24+0.195 \sin \theta] \\ R & =0.24+0.195 \sin 22.6= \\ 0.24 & +0.195 \times \frac{5}{13}=0.315 \\ \quad & =\frac{63}{200} \end{aligned} \end{aligned}$ |
| :--- |
| Coefficient $\mu=4 / 7$ or 0.571 | \& | M1 |
| :--- |
| A1 |
| M1 |
| A1 |
| M1 |
| A1 | \& 6 \& | For resolving forces horizontally |
| :--- |
| For resolving forces vertically |
| For using $\mu=F / R$ | \\

\hline
\end{tabular}

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| (ii) | $\begin{aligned} & R=0.24-0.195 \sin 22.6 \\ &=0.24-0.195 \times \frac{5}{13} \\ &=0.165=\frac{33}{200} \\ & \\ & 0.195 \times \frac{12}{13}-\left(\frac{4}{7}\right) \times 0.165 \\ & \quad=0.024 a \end{aligned}$ <br> Acceleration is $3.57 \mathrm{~ms}^{-2}$ | B1 <br> M1 <br> A1 <br> A1 | 4 | For using Newton's second law for motion along the rod <br> Allow acceleration $=25 / 7$ |
| :---: | :---: | :---: | :---: | :---: |
| $7 \quad$ (i) | $[\mathrm{WD}=14000 \times 25]$ <br> Work done is 350 kJ or 350000 J | $\begin{aligned} & \text { M1 } \\ & \text { A1 } \end{aligned}$ | 2 | For using $P=\mathrm{WD} \div \Delta t$ |
| (ii) | $\begin{gathered} 14000 / v_{\mathrm{A}}-235=1600 \times 0.5 \rightarrow \\ v_{\mathrm{A}}=13.53 \mathrm{~ms}^{-1} \\ 14000 / v_{\mathrm{B}}-235=1600 \times 0.25 \rightarrow \\ v_{\mathrm{B}}=22.05 \mathrm{~ms}^{-1} \\ {[\text { KE gain }=} \\ \left.1 / 21600\left(22.05^{2}-13.53^{2}\right)\right] \\ \text { KE gain }=242.5 \mathrm{~kJ} \text { or } 242500 \mathrm{~J} \end{gathered}$ | $\begin{aligned} & \text { M1 } \\ & \text { A1 } \\ & \text { A1 } \\ & \text { M1 } \\ & \text { A11 } \end{aligned}$ | 5 | For using DF $=P / v$ and Newton's $2^{\text {nd }}$ law to find the speed of the car at $A$ or at $B$ $v_{\mathrm{A}}=2800 / 207$ $v_{\mathrm{B}}=2800 / 127$ <br> For using KE gain $=1 / 2 m\left(v_{\mathrm{B}}^{2}-v_{\mathrm{A}}^{2}\right)$ |
| (iii) | $350000=242500+235 \times A B$ <br> Distance $A B$ is 457 m | M1 <br> A1 $\sqrt{\wedge}$ <br> A1 | 3 | For using WD by DF $=\mathrm{KE}$ gain + resistance $\times A B$ |

